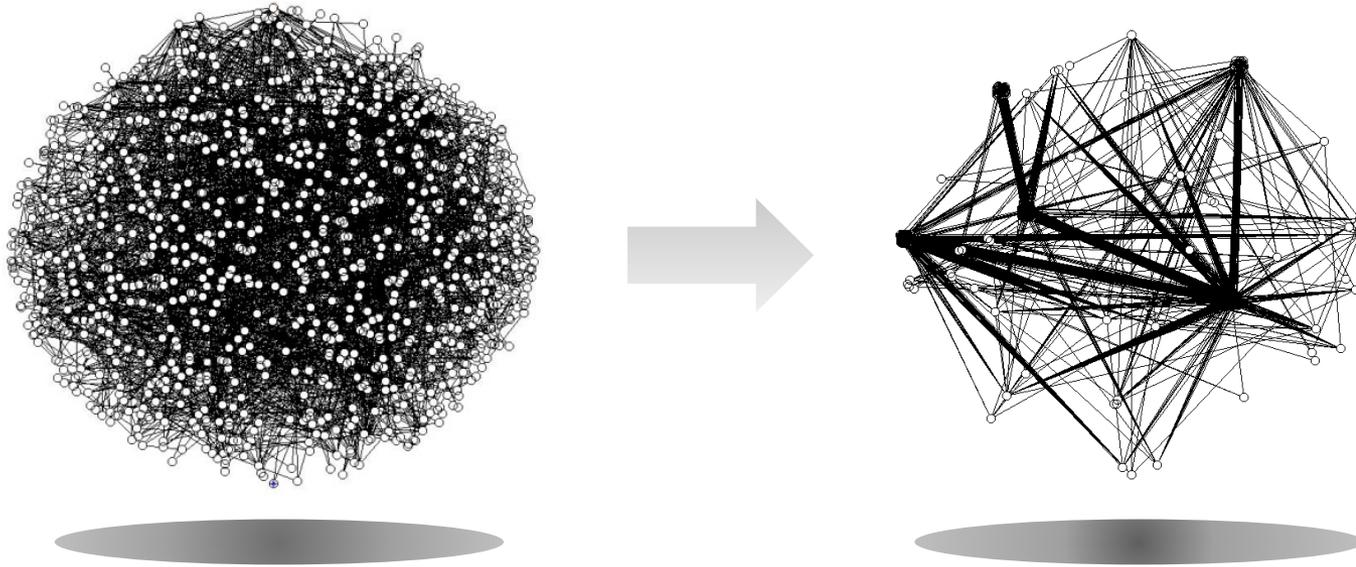


Clustered Model Reduction of Interconnected Second-Order Systems and Its Applications to Power Systems



Takayuki Ishizaki, Jun-ichi Imura (Tokyo Inst. of Tech.)



Outline

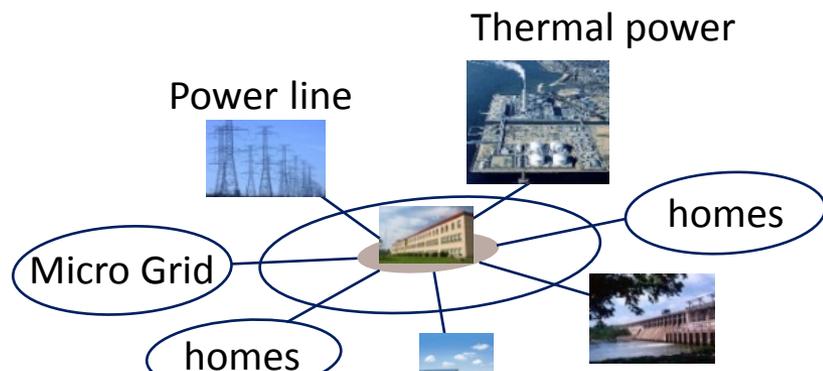
- ▶ **Introduction: Why clustered model reduction?**
- ▶ Clustered Model Reduction Theory
 - ▶ Interconnected first-order systems
 - ▶ Extension to second-order networks
- ▶ Application to power networks
- ▶ Conclusion



Control of Large-Scale Networks

Power Networks

- ▶ Tokyo area: **20 million** houses
 - ▶ **Instability** may be caused by renewables such as PV, wind

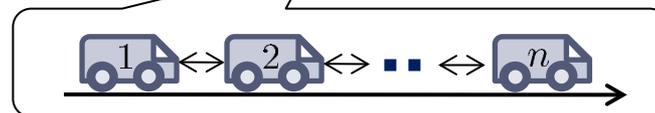


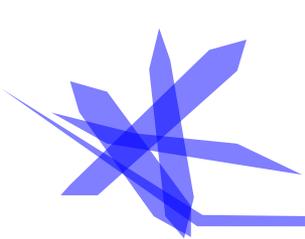
Model reduction is one prospective approach

- ▶ Center of Tokyo area: **5 million** cars
 - ▶ **Heavy traffic jam**



How to manage?





Standard Model Reduction Framework

$$\checkmark PP^\dagger = I_{\hat{n}}$$

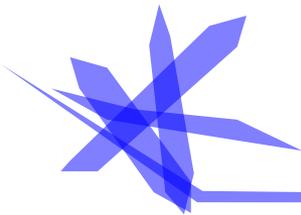
$$\Sigma : \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \\ x \in \mathbb{R}^n \end{cases} \xrightarrow[\boxed{P} \in \mathbb{R}^{\hat{n} \times n}]{Px = \hat{x}} \hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^\dagger \hat{x} + PBu \\ \hat{y} = CP^\dagger \hat{x} \\ \hat{x} \in \mathbb{R}^{\hat{n}}, \hat{n} < n \end{cases}$$

Main goal: Find P such that $\|y - \hat{y}\|$ is small enough

+ stability of error systems, error analysis, low computation cost

Standard methods:

- ▶ Balanced truncation, Hankel norm approximation
 - ▶ error bound, stability preservation 😊 **high computational cost** 😞
- ▶ Krylov projection
 - ▶ lower computation cost 😊 **possibly unstable model, no error bound** 😞

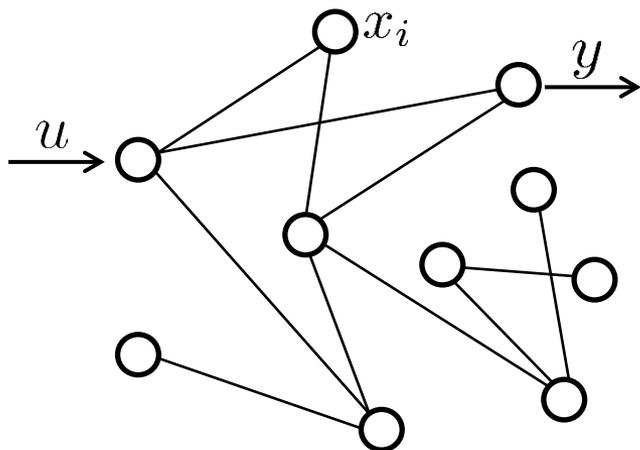


Application of Standard Methods to Network Systems

Drawback: Network structure is lost through reduction

Network system

$$\Sigma : \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases}$$



Sparse 😊

Reduced model

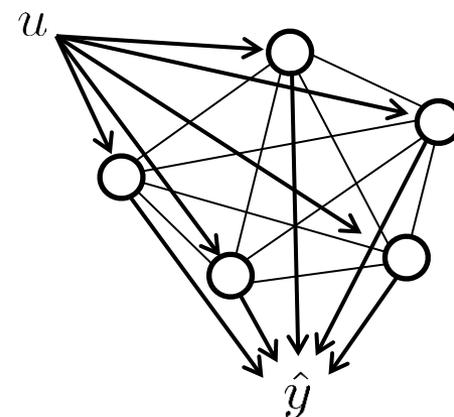
$$\hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^\dagger \hat{x} + PBu \\ \hat{y} = CP^\dagger \hat{x} \end{cases}$$

$$Px = \hat{x}$$

\longrightarrow

$$P \in \mathbb{R}^{\hat{n} \times n}, \hat{n} < n$$

Dense matrix



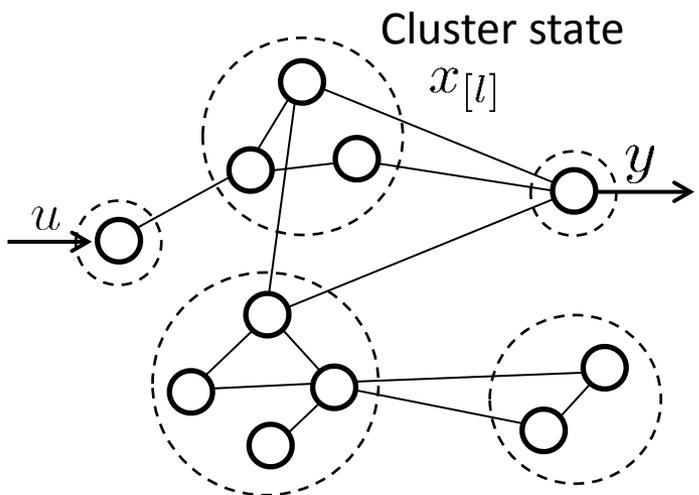
Dense 😞



Clustered Model Reduction

Network system

$$\Sigma : \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases}$$



Sparse 😊

Aggregated model

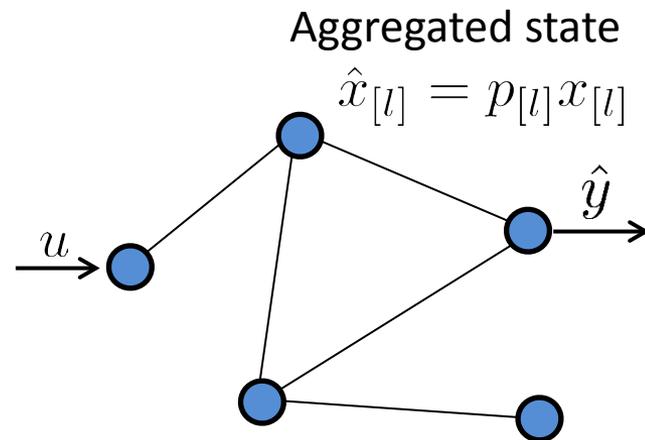
$$\hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^\dagger \hat{x} + PBu \\ \hat{y} = CP^\dagger \hat{x} \end{cases}$$

$$Px = \hat{x}$$



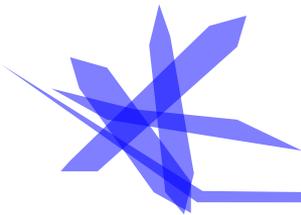
$p[l]$: row vector

$$P = \begin{bmatrix} p[1] & & & \\ & p[2] & & \\ & & \dots & \end{bmatrix}$$



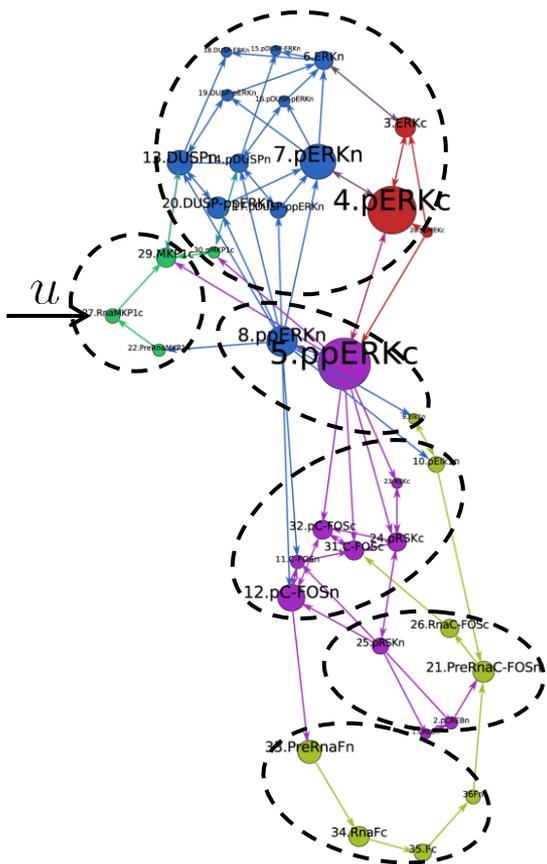
Sparse 😊

Preservation of network structure among **clusters**

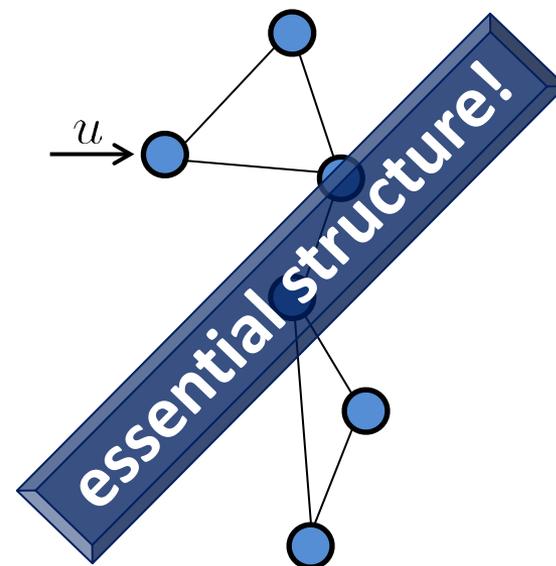
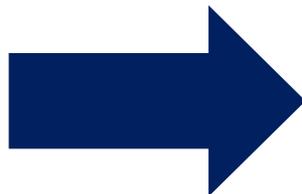


Why Clustered Model Reduction?

Gene Network [Mochizuki et al. , J. Theoretical Biology (2010)]



Clustered model reduction



Extract essential structure
to study mechanism of functions



Outline

- ▶ Introduction: Why clustered model reduction?
- ▶ **Clustered Model Reduction Theory**
 - ▶ **Interconnected first-order systems**
 - ▶ Extension to second-order networks
- ▶ Application to power networks
- ▶ Conclusion

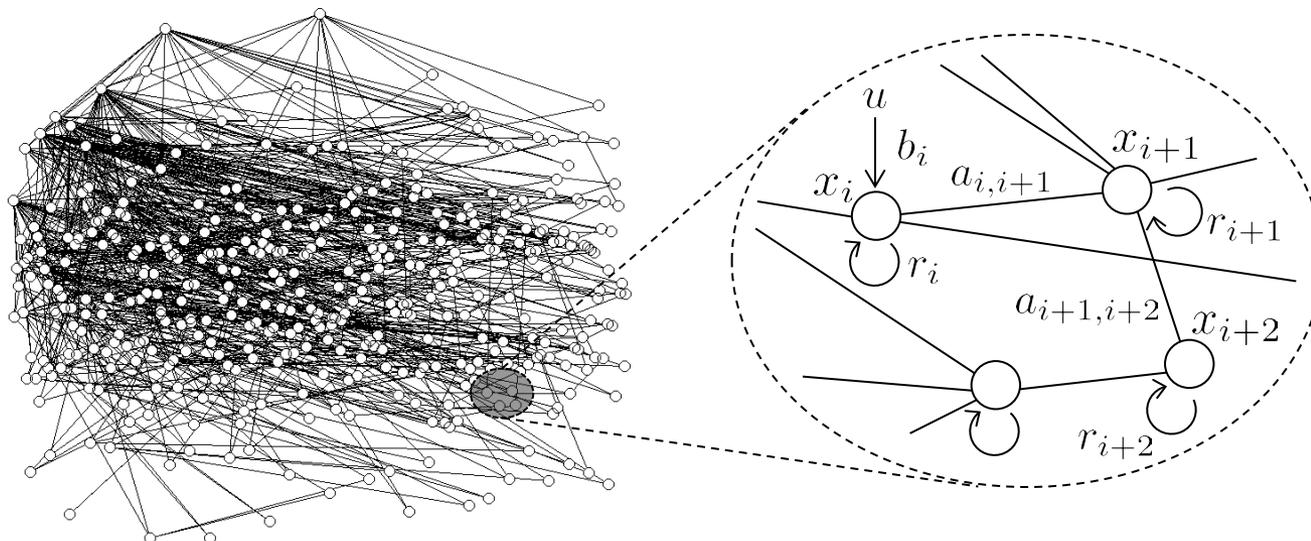


System Description (First-Order Subsystems)

[Definition] Bidirectional Network

$\dot{x} = Ax + Bu$ with $A = \{a_{i,j}\} \in \mathbb{R}^{n \times n}$ and $B = \{b_i\} \in \mathbb{R}^n$ is said to be bidirectional network if A is **symmetric** and **stable**.

Reaction-diffusion systems: $\dot{x}_i = -r_i x_i + \sum_{j=1, j \neq i}^n a_{i,j} (x_j - x_i) + b_i u$



Clustered Model Reduction Problem

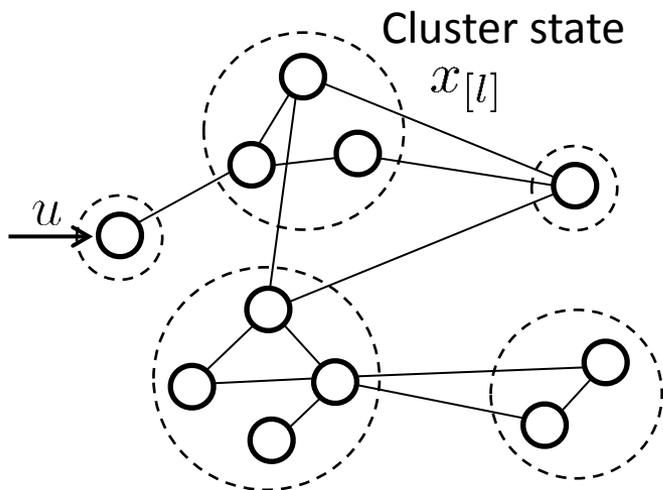
[Problem] Given $\epsilon \geq 0$, find a **cluster set** $\{\mathcal{I}_{[l]}\}_{l \in \mathbb{L}}$ such that

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \epsilon$$

where $g(s) := (sI_n - A)^{-1}B$ and $\hat{g}(s) := P^\top (sI_{\hat{n}} - PAP^\top)^{-1}PB$.

Bidirectional network

$$\Sigma : \dot{x} = Ax + Bu$$



Sparse 😊

$$Px = \xi$$

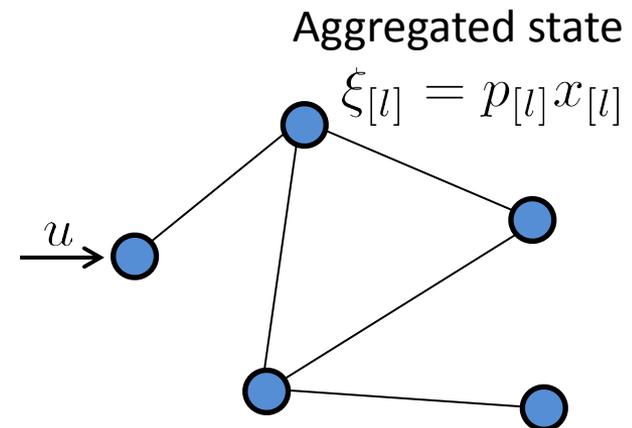


$$P = \text{Diag}(p_{[1]}, \dots, p_{[\hat{n}]})$$

$$p_{[l]} = \frac{1}{\sqrt{|\mathcal{I}_{[l]}|}} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}^\top$$

Aggregated model

$$\hat{\Sigma} : \begin{cases} \dot{\xi} = PAP^\top \xi + PBu \\ \hat{x} = P^\top \xi \end{cases}$$

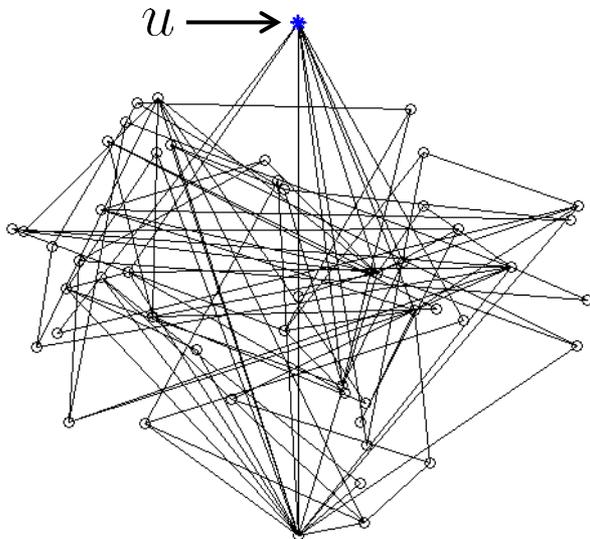


Sparse 😊



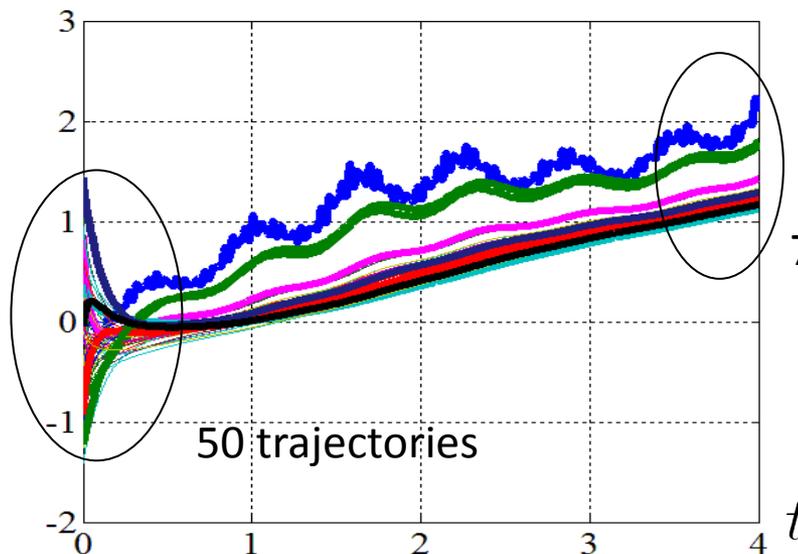
How to Formulate Reducibility?

Bidirectional network $\dot{x} = Ax + Bu$



50 nodes, nonzero $a_{i,j}$ is randomly chosen from $(0, 1]$

[State trajectory under random u]



7 clusters

$$x_i(t) - x_j(t) \equiv 0, \quad \forall u(t)$$

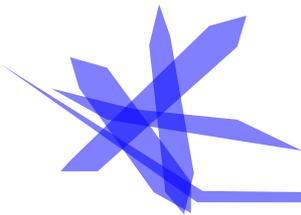
Local uncontrollability!



[Definition] Reducible cluster

A cluster $\mathcal{I}_{[l]}$ is said to be reducible if under **any input signal $u(t)$**

$$x_i(t) \equiv x_j(t), \quad \forall i, j \in \mathcal{I}_{[l]}.$$



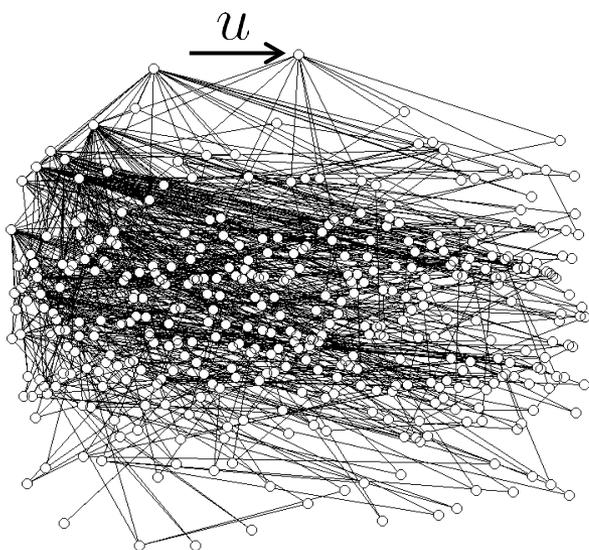
Positive Tridiagonalization

[Lemma] For every bidirectional network (A, B) , there exists a unitary $H \in \mathbb{R}^{n \times n}$ such that $(\tilde{A}, \tilde{B}) = (H^T A H, H^T B)$ has the following structure.

Bidirectional network (A, B)

$$\dot{x} = Ax + Bu, \quad A = A^T$$

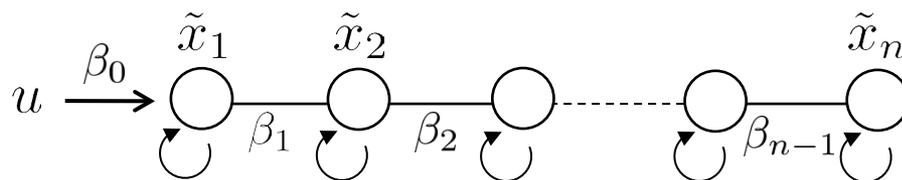
(not necessarily positive)



$$x = H\tilde{x}$$



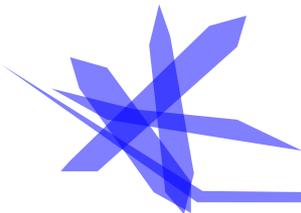
Positive tridiagonal realization (\tilde{A}, \tilde{B})



$$\tilde{A} = \begin{bmatrix} \alpha_1 & \beta_1 & & & \\ \beta_1 & \alpha_2 & \beta_2 & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \ddots & \beta_{n-1} \\ & & & \beta_{n-1} & \alpha_n \end{bmatrix} \quad \tilde{B} = \begin{bmatrix} \beta_0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

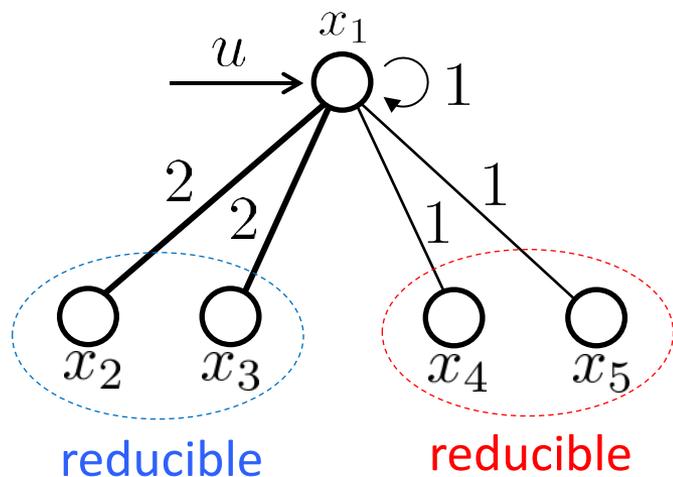
Metzler

$$\checkmark \beta_i \geq 0$$



Reducibility Characterization

Bidirectional network (A, B)

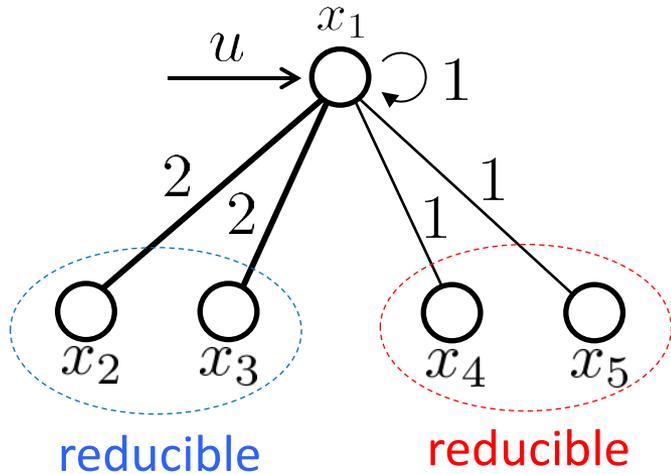


$$A = \begin{bmatrix} -(6 + 1) & 2 & 2 & 1 & 1 \\ 2 & -2 & 0 & 0 & 0 \\ 2 & 0 & -2 & 0 & 0 \\ 1 & 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

— (graph Laplacian + diagonal)

Reducibility Characterization

Bidirectional network (A, B)



(\tilde{A}, \tilde{B}) : positive tridiagonal realization
 H : transformation matrix

Index matrix

$$\Phi := H \text{diag}(-\tilde{A}^{-1} \tilde{B})$$

Characterization in frequency domain

$$\Phi = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1.20 & -0.20 & 0 & 0 \\ 0 & 1.20 & -0.20 & 0 & 0 \\ 0 & 0.60 & 0.40 & 0 & 0 \\ 0 & 0.60 & 0.40 & 0 & 0 \end{bmatrix}$$

} identical
} identical



Equivalent characterization of cluster reducibility

θ -Reducible Cluster Aggregation

[Definition] θ -Reducibility of Clusters

A cluster $\mathcal{I}_{[l]}$ is said to be θ -reducible if

$$\|\text{row}_i[\Phi] - \text{row}_j[\Phi]\|_{l_\infty} \leq \theta, \quad \forall i, j \in \mathcal{I}_{[l]}$$

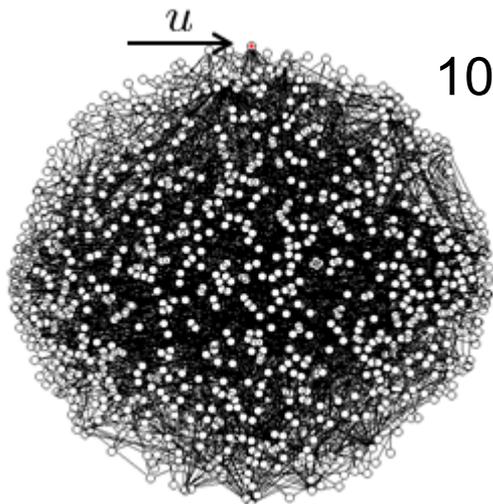
$x_i(t) - x_j(t) \simeq 0, \quad \forall u(t)$
Similar behavior

[Theorem] If all clusters are θ -reducible, then

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \gamma \sqrt{\sum_{l=1}^{\hat{n}} |\mathcal{I}_{[l]}| (|\mathcal{I}_{[l]}| - 1) \theta}$$

where $\gamma := \|(PAP^\top)^{-1}PA\|$.

θ : coarseness parameter



1000 nodes

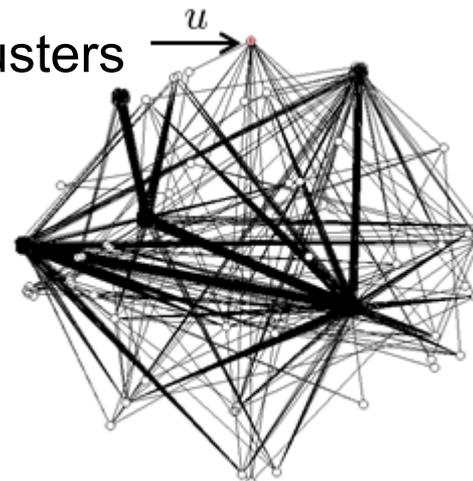
aggregation



$\theta = 1.5$

about 5% error

47 clusters



Extract essential cluster structure!





Outline

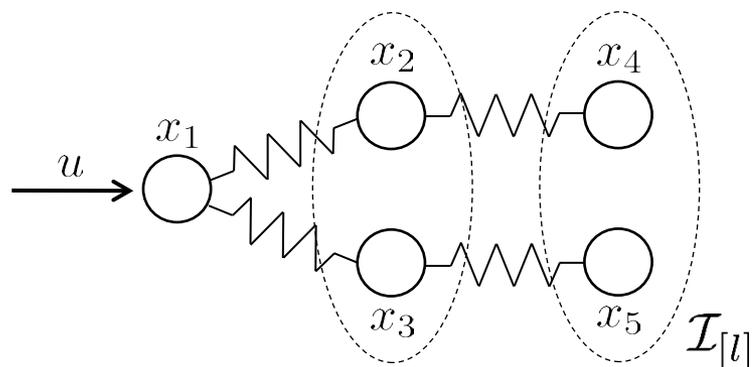
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Formulation by Second-Order Systems

Second-order networks

$$\Sigma : \ddot{x} + D\dot{x} + Kx = fu$$

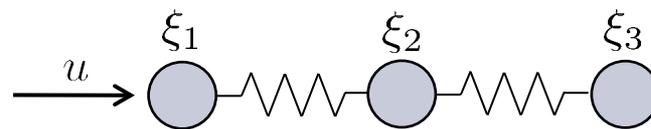


$$Px = \xi$$



Aggregated model

$$\hat{\Sigma} : \begin{cases} \ddot{\xi} + PDP^T\dot{\xi} + PKP^T\xi = Pfu \\ \hat{x} = P^T\xi \end{cases}$$



[Problem] Given $\epsilon \geq 0$, find a cluster set $\{\mathcal{I}_{[l]}\}_{l \in \mathbb{L}}$ such that

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \epsilon$$

where $g(s) := (s^2 I_n + sD + K)^{-1} f$ and $\hat{g}(s) := P^T (s^2 I_{\hat{n}} + sPDP^T + PKP^T)^{-1} Pf$.



Extension to Second-Order Networks

First-order representation (2n-dim. system) ✓ $X := \begin{bmatrix} x \\ \dot{x} \end{bmatrix}$

$$\Sigma : \begin{cases} \dot{X} = AX + Bu \\ x = CX \end{cases} \quad \text{where} \quad A := \begin{bmatrix} 0 & I_n \\ -K & -D \end{bmatrix} \quad B := \begin{bmatrix} 0 \\ f \end{bmatrix} \quad C := \begin{bmatrix} I_n & 0 \end{bmatrix}$$

Index matrix $\Phi = \begin{bmatrix} \Phi_1 \\ \Phi_2 \end{bmatrix} \in \mathbb{R}^{2n \times 2n}$ w.r.t. $\begin{cases} \text{position } x \\ \text{velocity } \dot{x} \end{cases}$

[Definition] A cluster $\mathcal{I}_{[l]}$ is said to be θ -reducible if

$$\|\text{row}_i[\Phi_k] - \text{row}_j[\Phi_k]\|_{l_\infty} \leq \theta, \quad \forall i, j \in \mathcal{I}_{[l]}, k \in \{1, 2\}$$

[Theorem] If all clusters are θ -reducible, then

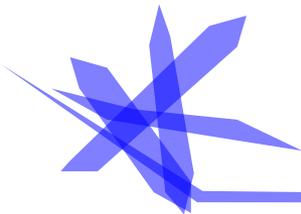
$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \gamma \sqrt{\sum_{l=1}^{\hat{n}} |\mathcal{I}_{[l]}| (|\mathcal{I}_{[l]}| - 1) \theta}$$

where $\gamma := \sqrt{2} \|P(s^2 I_{\hat{n}} + sPDP^\top + PKP^\top)^{-1} [PK \ PD] - [I_n \ 0]\|_{\mathcal{H}_\infty}$.



Outline

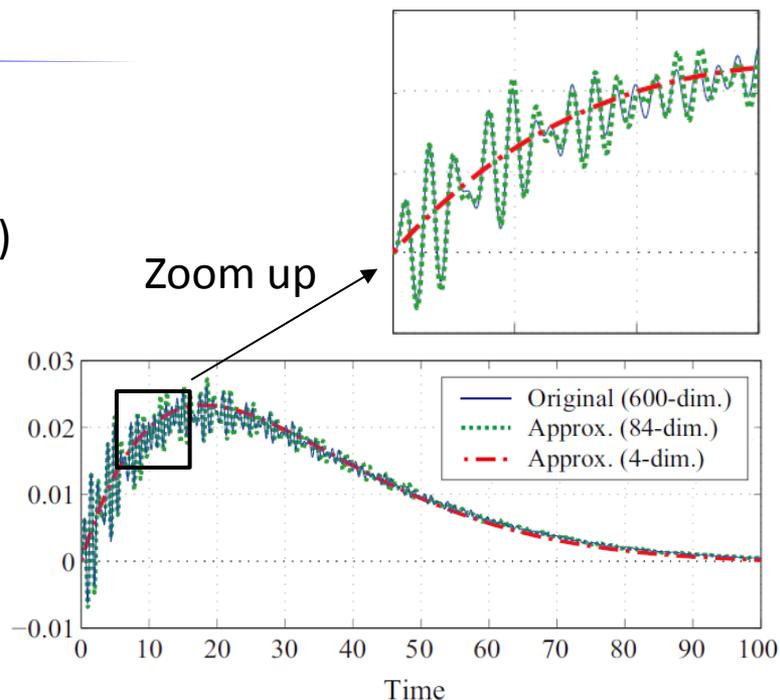
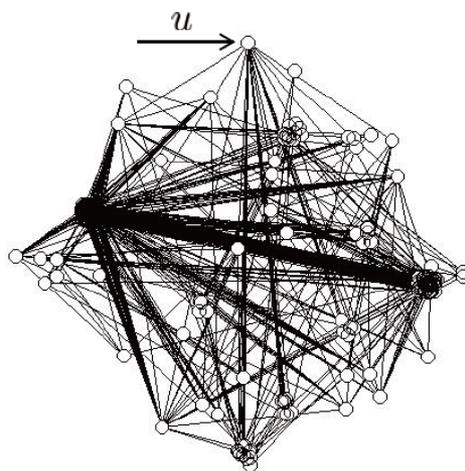
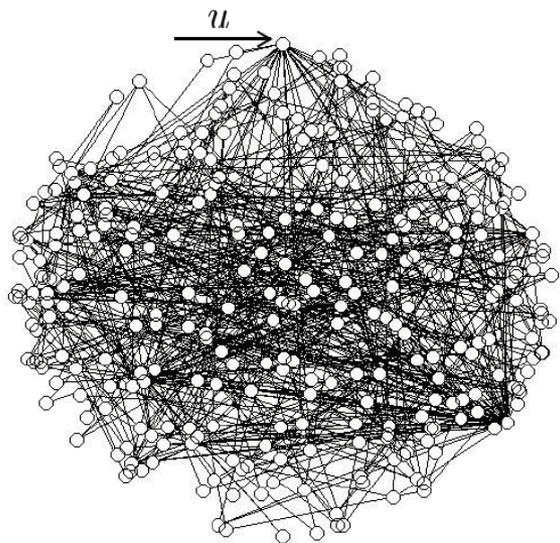
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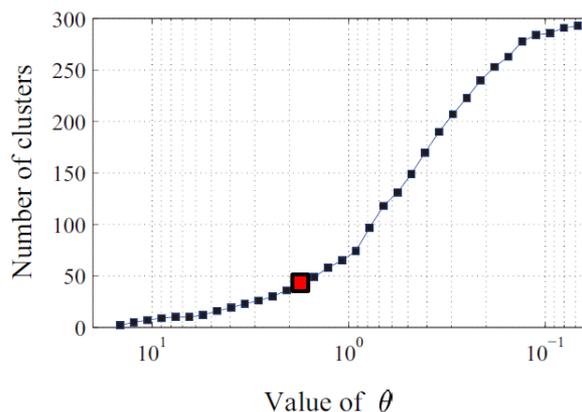
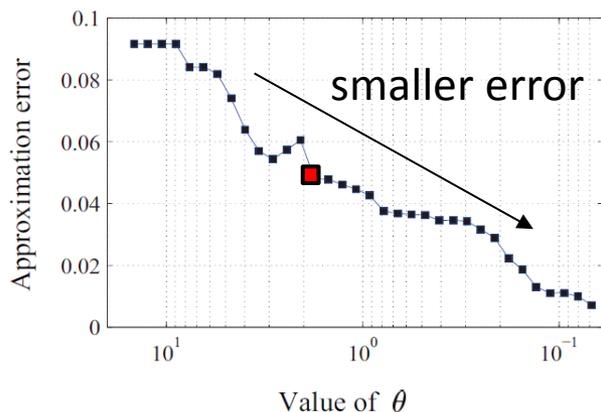
Numerical Example

Power network modeled by swing equation

Original network (300 nodes) Agg. model (42 clusters)



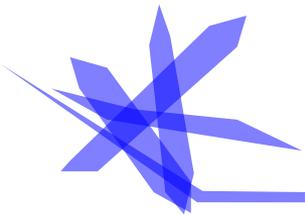
Position trajectory of a mass



Relative error

$$\frac{\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty}}{\|g(s)\|_{\mathcal{H}_\infty}} = 4.81\%$$

when $\theta = 1.76$



Concluding Remarks

- ▶ Clustered model reduction
 - ▶ extract essential information on input-to-state mapping
 - ▶ application to power networks model by swing equation
- ▶ Future works
 - ▶ application to more realistic power networks
 - ▶ extension to nonlinear systems
 - ▶ application to control system design

[T. Ishizaki et al. IEEE TAC (2014)], [T. Ishizaki et al. NOLTA (2015)], My website, etc.

Thank you for your attention!